CS 240 – Data Structures and Data Management

Module 4: Dictionaries

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Spring 2024

version 2024-05-27 11:34

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- AVI insertion revisited
- **Deletion in AVI Trees**

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ADT Dictionary (review)

Dictionary: An ADT consisting of a collection of items, each of which contains

 \bullet a key

• some *data* (the "value")

and is called a key-value pair (KVP). Keys can be compared and are (typically) unique.

Operations:

- \bullet search(k) (also called lookup(k))
- \bullet insert(k, v)
- delete(k) (also called remove(k)))
- o optional: successor, join, is-empty, size, etc.

Examples: symbol table, license plate database

Elementary Realizations (review)

Common assumptions:

- Dictionary has *n* KVPs
- Each KVP uses constant space (if not, the "value" could be a pointer)
- Keys can be compared in constant time

Unordered array or linked list

search $\Theta(n)$ *insert* $\Theta(1)$ (except array occasionally needs to resize) delete $\Theta(n)$ (need to search)

Ordered array

search Θ(log n) (via binary search) insert $\Theta(n)$ delete Θ(n)

Binary Search (review)

Only applies to a *sorted array*:

We will return to binary search (and sometimes improve it!) later.

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Binary Search Trees (review)

Structure Binary tree: all nodes have two (possibly empty) subtrees Every node stores a KVP Empty subtrees usually not shown

Ordering Every key k in T*.*left is less than the root key. Every key k in T*.*right is greater than the root key.

 $\sqrt{ }$ In our examples we only show the keys, and we show them directly in the node. A more accurate picture would be $\left(\bullet \right)$ $\left(\star \right)$ key = 15, <other info>

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 $BST::search(k)$ Start at root, compare k to current node's key. Stop if found or subtree is empty, else recurse at subtree. BST::insert(k, v) Search for k , then insert (k, v) as new node

Example: BST::insert(24*,* v)

- \bullet First search for the node x that contains the key.
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Height of a BST

 $BST::search$, $BST::insert$, $BST::delete$ all have cost $\Theta(h)$, where $h =$ height of the tree $=$ max. path length from root to leaf

If n items are inserted one-at-a-time, how big is h ?

• Work-case:
$$
n-1 = \Theta(n)
$$

• Best-case: $\Theta(\log n)$. Any binary tree with *n* nodes has height $h \geq \log(n+1) - 1$ (Layer *i* has at most 2^{*i*} nodes. So $n \leq \sum_{i=0}^{h} 2^{i} = 2^{h+1} - 1$).

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Goal: Create subclasses of BSTs where the height is always good.

- Impose a structural property.
- Argue that the property implies logarithmic height.
- Discuss how to maintain the property during operatons.

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AVL Trees

Introduced by Adel'son-Vel'ski˘ı and Landis in 1962, an **AVL Tree** is a BST with an additional **height-balance property** at every node: The heights of the left and right subtree differ by at most 1.

Rephrase: If node v has left subtree L and right subtree R , then

balance(v) := height(R) – height(L) must be in $\{-1, 0, 1\}$ balance(v) = -1 means v is left-heavy

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 \bullet Need to store at each node ν the height of the subtree rooted at it

(There are ways to implement AVL-trees where we only store *balance*(v), $\bigg($ so fewer bits. But the code gets more complicated (no details).

AVL tree example

(The lower numbers indicate the height of the subtree.)

AVL tree example

Alternative: store balance (instead of height) at each node.

Height of an AVL tree

Theorem: An AVL tree on n nodes has Θ(log n) height.

 \Rightarrow search, BST::insert, BST::delete all cost $\Theta(\log n)$ in the worst case!

Proof:

- \bullet Define $N(h)$ to be the *least* number of nodes in a height-h AVL tree.
- What is a recurrence relation for $N(h)$?
- What does this recurrence relation resolve to?

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AVL insertion

- To perform AVL::insert(k*,* v):
	- First, insert (k, v) with the usual BST insertion.
	- We assume that this returns the new leaf z where the key was stored.
	- Then, move up the tree from z.

We assume for this that we have parent-links. This can be avoided if BST ::insert returns the full path to z. \setminus

Update height (easy to do in constant time):

setHeightFromSubtrees(u)

- 1. u *.height* $\leftarrow 1 + \max\{u$ *.left.height,* u *.right.height*}
- If the height difference becomes ± 2 at node z, then z is **unbalanced**. Must re-structure the tree to rebalance.

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Changing structure without changing order

Note: There are many different BSTs with the same keys.

Goal: Change the structure locally nodes without changing the order.

Longterm goal: Restructure such the subtree becomes balanced.

Right Rotation

This is a **right rotation** on node z:

(Notation $\stackrel{p}{\leftarrow}$ means 'also change parent-reference of right-hand-side')

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Why do we call this a rotation?

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Left Rotation

Symmetrically, this is a **left rotation** on node z:

Again, only two links need to be changed and two heights updated. Useful to fix right-right imbalance.

Double Right Rotation

This is a **double right rotation** on node z:

First, a left rotation at c.

Double Right Rotation

This is a **double right rotation** on node z:

First, a left rotation at c. Second, a right rotation at z.

Double Left Rotation

Symmetrically, there is a **double left rotation** on node z:

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AVL Insertion Example revisited

AVL insertion revisited

- Imbalance at z: do (single or double) rotation
- Choose c as child where subtree has bigger height.

```
AVL::insert(k, v)
 1. z \leftarrow \text{BST::insert}(k, v) // leaf where k is now stored
2. while (z is not NULL)
3. if (|z.left.height − z.right.height| > 1) then
4. Let c be taller child of z
5. Let g be taller child of c (so grandchild of z)
6. restructure(g, c, z) // see later
7. break // can argue that we are done
8. setHeightFromSubtrees(z)
9. z \leftarrow z. parent
```
Can argue: For insertion one rotation restores all heights of subtrees. \Rightarrow No further imbalances, can stop checking.

Fixing a slightly-unbalanced AVL tree

Rule: The middle key of g*,* c*,* z becomes the new root.

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AVL Deletion

Remove the key k with *BST::delete.*

Find node where *structural* change happened.

(This is not necessarily near the node that had k .) Go back up to root, update heights, and rotate if needed.

```
AVL::delete(k)
1. z \leftarrow \text{BST::delete}(k)2. // Assume z is the parent of the BST node that was removed
3. while (z is not NULL)
4. if (|z.left.height − z.right.height| > 1) then
5. Let c be taller child of z
6. Let g be taller child of c (break ties to avoid double rotation)
7. z \leftarrow \text{restructure}(g, c, z)8. // Always continue up the path
9. setHeightFromSubtrees(z)
10. z \leftarrow z. parent
```


A single restructure is not enough to restore all balances.

Important: Ties *must* be broken to avoid double rotation. Consider again the above example. If we applied double-rotation:

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Violation is below where we check further.

AVL Tree Summary

search: Just like in BSTs, costs Θ(height)

insert: BST::insert, then check & update along path to new leaf

- **•** total cost Θ (*height*)
- restructure will be called at most once.

delete: BST::delete, then check & update along path to deleted node

- total cost Θ (height)
- restructure may be called Θ (height) times.

Worst-case cost for all operations is Θ (height) = Θ (log n).

- In practice, the constant is quite large.
- \bullet Other realizations of ADT Dictionary are better in practice (\rightarrow later)